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One-point Gleason parts and point derivations in uniform algebras

by

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Abstract. It is shown that a uniform algebra can have a nonzero bounded point derivation while having no nontrivial Gleason parts. Conversely, a uniform algebra can have a nontrivial Gleason part while having no nonzero, even possibly unbounded, point derivations.

1. Introduction. Let X be a compact Hausdorff space, and let $C(X)$ be the algebra of all continuous complex-valued functions on X with the supremum norm $\|f\| = \sup\{|f(x)| : x \in X\}$. A *uniform algebra* A on X is a closed subalgebra of $C(X)$ that contains the constant functions and separates the points of X . There is a general feeling that a uniform algebra A on X either is $C(X)$ or else there is a subset of the maximal ideal space of A that can be given the structure of a complex manifold on which the functions in A are holomorphic. However, it is well known that this feeling is not completely correct. One is therefore led to consider weaker forms of analytic structure. Perhaps the two most common of these are nonzero point derivations and nontrivial Gleason parts. Thus the question arises as to how these two weak forms of analytic structure are related. More precisely, does the presence of one of them imply the presence of the other? The main purpose of this paper is to show that the answer is *no*: either form can be present in the absence of the other.

THEOREM 1.1. *There exists a uniform algebra B on a compact metrizable space such that there exists a nonzero bounded point derivation on B but B has no nontrivial Gleason parts.*

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THEOREM 1.2. *There exists a uniform algebra B on a compact Hausdorff space such that B has a nontrivial Gleason part but there are no nonzero point derivations on B .*

These two results are new. However, Theorem 1.2 and its proof below were found by Garth Dales and Joel Feinstein in response to a question posed to them by the second author. We thank Dales and Feinstein for allowing us to present their result in our paper so that the complementary Theorems 1.1 and 1.2 appear together in a single paper.

Note that the algebra in Theorem 1.1 has a nonzero *bounded* point derivation while the algebra in Theorem 1.2 not only has no nonzero bounded point derivations but moreover has no nonzero, possibly unbounded, point derivations. In fact, a uniform algebra with a nontrivial Gleason part but no nonzero *bounded* point derivations was constructed by John Wermer long ago [12]. Wermer's example is $R(K)$ for a certain compact planar set K . Such a uniform algebra necessarily has nonzero *unbounded* point derivations [1, Corollary 3.3.11 and Theorem 3.3.3].

Obviously Theorems 1.1 and 1.2 contain the weaker statement that *at a particular point x* of the maximal ideal space of a uniform algebra the condition that there is a nonzero point derivation at x and the condition that x lies in a nontrivial Gleason part are independent of each other. The statement that there need not be a nonzero point derivation at a point in a nontrivial Gleason part seems to be new. That a point at which there is a nonzero bounded point derivation need not belong to a nontrivial Gleason part was shown by Stuart Sidney long ago [10, Example 5.13]. However, in contrast to the algebra in Theorem 1.1, Sidney's uniform algebra does have nontrivial Gleason parts, and in fact, its maximal ideal space contains many analytic discs.

Theorem 1.2 should be contrasted with the theorem of Andrew Browder [2] (see also [1, Theorem 1.6.2]) that if a point x of the maximal ideal space \mathfrak{M}_B of a uniform algebra B is nonisolated in the metric topology on \mathfrak{M}_B , then there must be a nonzero (possibly unbounded) point derivation at x .

We will show that the uniform algebras in Theorems 1.1 and 1.2 can be taken to satisfy additional conditions. Specifically we will prove the following two results that contain Theorems 1.1 and 1.2.

THEOREM 1.3. *There exists a normal uniform algebra B on a compact metrizable space X and a point $x \in X$ such that B has a nondegenerate bounded point derivation of infinite order at x and B has bounded relative units at every point of $X \setminus \{x\}$.*

THEOREM 1.4. *For each integer $n \geq 2$, there exists a normal uniform algebra B on a compact Hausdorff space X such that B has a Gleason part P that has exactly n elements, B has bounded relative units at every point of $X \setminus P$, and there are no nonzero point derivations on B .*

That Theorems 1.3 and 1.4 strengthen Theorems 1.1 and 1.2 is a consequence of known results recalled in Section 2 below. The reader should compare Theorem 1.3 with [5, Theorems 5.1 and 5.3] of Feinstein.

In contrast to the situation in Theorems 1.1 and 1.3, it is unknown whether the space on which the uniform algebras in Theorems 1.2 and 1.4 are defined can be taken to be metrizable. It is well known that each point of a nontrivial Gleason part is a nonpeak point, and it seems to be a difficult open question whether there exist uniform algebras (with or without nontrivial Gleason parts) on a metrizable space having no nonzero, possibly unbounded, point derivations at a nonpeak point. If in Theorem 1.2 we relax the requirements on B to allow *unbounded* point derivations, then Wermer's example shows that metrizability can be achieved. Wermer's example does not satisfy the additional conditions given in Theorem 1.4. However, a modification of the proof of Theorem 1.4 shows that, subject to allowing unbounded point derivations, metrizability can be achieved there as well. In fact, more is true; the uniform algebra can be taken to be strongly regular. (It is a consequence of known results recalled in Section 2 below that there are no nonzero bounded point derivations on a strongly regular uniform algebra.)

THEOREM 1.5. *For each integer $n \geq 2$, there exists a strongly regular uniform algebra B on a compact metrizable space X such that B has a Gleason part P that has exactly n elements, and B has bounded relative units at every point of $X \setminus P$.*

In the next section we define various terms already used above and present other needed background and preliminary results. In Section 3 we discuss Brian Cole's method of root extensions, which we will use in constructing our examples. Finally, Theorems 1.1 and 1.3 are proved in Section 4, while Theorems 1.2, 1.4, and 1.5 are proved in Section 5. Notation introduced in Sections 2 and 3 will be used in Sections 4 and 5 without further comment.

2. Preliminaries. In this section we introduce terminology, notation, and conventions that we will use. We also present some results we will need.

Throughout the paper, all spaces will tacitly be required to be Hausdorff. Throughout this section, A will be a uniform algebra on a compact space X and x will be a point of X .

We tacitly regard X as a subspace of the maximal ideal space \mathfrak{M}_A of A by identifying each point of X with the corresponding point evaluation functional. When convenient, we will also tacitly regard A as a uniform algebra on \mathfrak{M}_A via the Gelfand transform. When clarity seems to require it, the Gelfand transform of a function f in A will be denoted in the customary way by \hat{f} .

The point x is said to be a *peak point* for A if there is a function f in A such that $f(x) = 1$ and $|f(y)| < 1$ for every $y \in X \setminus \{x\}$. The point x is said to be a *generalized peak point* if for every neighborhood U of x there exists a function f in A such that $f(x) = \|f\| = 1$ and $|f(y)| < 1$ for every $y \in X \setminus U$. When the space X is metrizable, the notions of peak point and generalized peak point coincide.

For $\phi \in \mathfrak{M}_A$ we define the ideals M_ϕ and J_ϕ by

$$M_\phi = \{f \in A : \widehat{f}(\phi) = 0\},$$

$$J_\phi = \{f \in A : \widehat{f}^{-1}(0) \text{ contains a neighborhood of } \phi \text{ in } \mathfrak{M}_A\}.$$

The uniform algebra A is *normal* on X if for each pair of disjoint closed subsets K_0 and K_1 of X there exists a function f in A such that $f|_{K_0} = 0$ and $f|_{K_1} = 1$. It is well known [11, Theorem 27.3] that if A is normal on X , then $X = \mathfrak{M}_A$. The uniform algebra A is *strongly regular at a point* x if J_x is dense in M_x . The uniform algebra A is *strongly regular* if it is strongly regular at every point of X . It was proved by Donald Wilken that every strongly regular uniform algebra is normal [13, Corollary 1].

The uniform algebra A has *bounded relative units* at the point x if there exists a positive constant C such that for each compact subset K of $X \setminus \{x\}$ there exists a function f in J_x such that $f|_K = 1$ and $\|f\| \leq C$. We will need the following result of Joel Feinstein [5, Proposition 1.5].

LEMMA 2.1. *If A has bounded relative units at x , then x is a generalized peak point for A and A is strongly regular at x .*

We will also need the following lemma of Feinstein and Heath [7, Lemma 4.3].

LEMMA 2.2. *Let A be a uniform algebra on a compact space Y , and let y be a point of Y . Suppose that, for each compact subset E of $Y \setminus \{y\}$, there exists a neighborhood U of y and a function $f \in A$ such that:*

- (i) $f|_U = 1$.
- (ii) $f|_E = 0$.
- (iii) *For each $k \in \mathbb{N}$ there is a $g \in A$ with $g^{2^k} = f$.*

Then A has bounded relative units at y .

An ideal is said to be *primary* if it is contained in a unique maximal ideal. (This use of the term *primary* is unrelated to its use in commutative algebra.) If I is a primary ideal contained in M_x , then I is said to be *local* if I contains J_x . (Observe that this condition is equivalent to the statement that whether a function $f \in A$ belongs to I depends only on the germ of f at x .) The notion of localness can be generalized to arbitrary ideals in A , but we omit the general definition as we will have no need of it. We will,

however, need the following standard result [4, Proposition 4.1.20(iv)] in the special case of primary ideals.

LEMMA 2.3. *Every ideal in a normal uniform algebra is local.*

The *Gleason parts* for the uniform algebra A are the equivalence classes in the maximal ideal space of A under the equivalence relation defined by $\phi \sim \psi$ if $\|\phi - \psi\| < 2$ in the norm on the dual space A^* . (That this really is an equivalence relation is well known but *not* obvious.) We say that a Gleason part is *nontrivial* if it contains more than one point.

The following lemma is standard (see [1, Lemma 2.6.1]).

LEMMA 2.4. *Two multiplicative linear functionals ϕ and ψ on a uniform algebra A lie in the same Gleason part if and only if*

$$\sup \{|\psi(f)| : f \in A, \|f\| \leq 1, \phi(f) = 0\} < 1.$$

For ϕ in \mathfrak{M}_A , a *point derivation* on A at ϕ is a linear functional d on A satisfying the identity

$$(2.1) \quad d(fg) = d(f)\phi(g) + \phi(f)d(g)$$

for all f and g in A . A point derivation is said to be *bounded* if it is bounded (continuous) as a linear functional. Now let n be a positive integer or ∞ . A *point derivation of order n* at ϕ is a sequence $d = (d^{(k)})_{k=0}^n$ of linear functionals on A such that for all f and g in A ,

$$(2.2) \quad d^{(0)}f = f(\phi),$$

$$(2.3) \quad d^{(k)}(fg) = \sum_{j=0}^k (d^{(j)}f)(d^{(k-j)}g) \quad \text{for all } k = 1, 2, \dots$$

The point derivation d is *bounded* if each $d^{(k)}$ is bounded. The point derivation d is *nondegenerate* if $d^{(1)} \neq 0$. We define the *kernel* $\ker d$ of the point derivation $d = (d^{(k)})_{k=0}^n$ by

$$\ker d = \{f \in A : d^{(k)}f = 0 \text{ for all } k = 0, 1, 2, \dots\}.$$

When d is nondegenerate, the functionals $d^{(0)}, d^{(1)}, d^{(2)}, \dots$ are linearly independent.

There is some ambiguity in our use of the term “point derivation” since it can refer either to a single linear functional satisfying equation (2.1) or a sequence of linear functionals satisfying equations (2.2) and (2.3). The careful reader will be able to discern which meaning is intended from the context. Clearly a linear functional $d^{(1)}$ that is a point derivation at ϕ can be identified with a point derivation $d = (d^{(k)})_{k=0}^1$ of order 1 at ϕ by taking $d^{(0)}$ to be the functional of evaluation at ϕ .

It is standard [1, p. 64] that a linear functional d on A is a point derivation at ϕ if and only if d annihilates M_ϕ^2 and the constant functions, and hence

there exists a nonzero point derivation at ϕ if and only if $M_\phi^2 \neq M_\phi$, and there exists a nonzero *bounded* point derivation at ϕ if and only if $\overline{M_\phi^2} \neq M_\phi$. It is elementary that the kernel of a point derivation $d = (d^{(k)})_{k=0}^n$ is an ideal, and for n finite, the kernel of d contains M_ϕ^{n+1} . Consequently, the kernel of a point derivation of finite order is a *primary* ideal. However, the kernel of a point derivation of infinite order can fail to be primary. The following simple consequence of Lemma 2.3 ensures, though, that on a normal uniform algebra even the kernel of a point derivation of infinite order is primary.

LEMMA 2.5. *Let A be a normal uniform algebra, and let $d = (d^{(k)})_{k=0}^n$ be a point derivation of order n , with $1 \leq n \leq \infty$, on A . Then $\ker d$ is a local, primary ideal.*

Proof. The ideal $\ker d$ is local by Lemma 2.3, and we have noted above that the kernel of every finite order point derivation is primary. We must show that $\ker d$ is primary in the case $n = \infty$. Denote the kernel of $d = (d^{(k)})_{k=0}^\infty$ by I , and for each finite $r = 1, 2, \dots$ denote the kernel of the finite order point derivation $(d^{(k)})_{k=0}^r$ by I_r . Then $I = \bigcap_{r=1}^\infty I_r$. Let x denote the point at which the derivation d is located. Then $I_r \supset J_x$ for every $r = 1, 2, \dots$. Therefore, $I \supset J_x$. Because A is normal, J_x is primary. Consequently, I is primary as well. ■

It is well known (and obvious from Lemma 2.4) that every generalized peak point is a one-point Gleason part. It is also well known that at a generalized peak point there are no nonzero point derivations [1, Sections 1–6].

We will achieve the strong regularity of the algebra in Theorem 1.5 by using a beautifully simple method from the paper [5] of Feinstein. Following his notation, we set $A_x = \overline{J}_x \oplus \mathbb{C} \cdot 1$ where $\mathbb{C} \cdot 1$ denotes the constant functions on X . The following two lemmas are contained in [5, Lemmas 4.1 and 4.3].

LEMMA 2.6. *Let the uniform algebra A be normal. Then A_x is a normal uniform algebra that is strongly regular at x .*

LEMMA 2.7. *Let the uniform algebra A be normal. Let y be a point of X distinct from x . Then $(A_x)_y = (A_y)_x = A_x \cap A_y$.*

We will need the following observation whose straightforward proof is left to the reader.

LEMMA 2.8. *Let the uniform algebra A be normal. Suppose A has bounded relative units at a point $y \in X$. Then A_x has bounded relative units at y as well.*

COROLLARY 2.9. *Let the uniform algebra A be normal, and let x_1, \dots, x_n be points of X .*

- (i) *At each of the points x_1, \dots, x_n , the uniform algebra $A_{x_1} \cap \dots \cap A_{x_n}$ is strongly regular.*
- (ii) *At each point of X where the algebra A has bounded relative units, so does $A_{x_1} \cap \dots \cap A_{x_n}$.*

Proof. By an induction argument left to the reader, it follows from Lemma 2.7 that for every permutation σ of x_1, \dots, x_n we have

$$A_{x_1} \cap \dots \cap A_{x_n} = (\dots((A_{\sigma(x_1)})_{\sigma(x_2)})_{\sigma(x_3)} \dots)_{\sigma(x_n)}.$$

The corollary is then immediate from Lemmas 2.6 and 2.8. ■

3. Cole's method of root extensions. Cole's method of root extensions involves an iterative process. We begin by discussing a single step of the iteration.

Let A be a uniform algebra on a compact space X , and let \mathcal{F} be a (nonempty) subset of A . Endow $\mathbb{C}^{\mathcal{F}}$ with the product topology. Let $p_1 : X \times \mathbb{C}^{\mathcal{F}} \rightarrow X$ and $p_f : X \times \mathbb{C}^{\mathcal{F}} \rightarrow \mathbb{C}$ denote the projections given by $p_1(x, (z_g)_{g \in \mathcal{F}}) = x$ and $p_f(x, (z_g)_{g \in \mathcal{F}}) = z_f$. Define $X_{\mathcal{F}} \subset X \times \mathbb{C}^{\mathcal{F}}$ by

$$X_{\mathcal{F}} = \{y \in X \times \mathbb{C}^{\mathcal{F}} : (p_f(y))^2 = f(p_1(y)) \text{ for all } f \in \mathcal{F}\},$$

and let $A_{\mathcal{F}}$ be the uniform algebra on $X_{\mathcal{F}}$ generated by the set of functions $\{f \circ p_1 : f \in A\} \cup \{p_f : f \in \mathcal{F}\}$. On $X_{\mathcal{F}}$ we have $p_f^2 = f \circ p_1$ for every $f \in \mathcal{F}$. Set $\pi = p_1|_{X_{\mathcal{F}}}$, and note that π is surjective. There is an isometric embedding $\pi^* : A \rightarrow A_{\mathcal{F}}$ given by $\pi^*(f) = f \circ \pi$.

We call the uniform algebra $A_{\mathcal{F}}$, or the pair $(A_{\mathcal{F}}, X_{\mathcal{F}})$, the \mathcal{F} -extension of A , and we call π the *associated surjection*. Note that if X is metrizable and \mathcal{F} is countable, then $X_{\mathcal{F}}$ is metrizable also. By [3, Theorem 1.6], if $X = \mathfrak{M}_A$, then $X_{\mathcal{F}} = \mathfrak{M}_{A_{\mathcal{F}}}$. For $x \in X$, if \mathcal{F} is contained in M_x , then the set $\pi^{-1}(x)$ consists of a single point.

There is an operator $S : A_{\mathcal{F}} \rightarrow \pi^*(A)$ given by integrating over the fibers of π using the measure on each fiber that is invariant under the obvious action of $(\mathbb{Z}/2)^{\mathcal{F}}$ on each fiber. See [3] or [11, pp. 194–195] for details. Rather than working with S , we will use the operator $T : A_{\mathcal{F}} \rightarrow A$ obtained from S by identifying $\pi^*(A)$ with A . The following properties of T are almost obvious.

LEMMA 3.1.

- (i) $\|T\| = 1$.
- (ii) $T \circ \pi^*$ is the identity.
- (iii) Given distinct functions $f_1, \dots, f_r \in \mathcal{F}$ and a function $f \in A$,

$$T(\pi^*(f)p_{f_1} \cdots p_{f_r}) = 0.$$

The following is contained in [5, Theorem 2.4].

LEMMA 3.2. *If A is normal, then so is $A_{\mathcal{F}}$.*

One can iterate the above extension process to obtain an infinite sequence of uniform algebras and then take a direct limit to obtain another uniform algebra. That is the procedure we will use to obtain the examples in Theorems 1.1 and 1.3. However, for some purposes that procedure is inadequate and transfinite induction is needed to obtain the desired algebra; this is the case in the proof of Theorems 1.2 and 1.4. Then the notion of a system of root extensions is needed.

Let τ be a fixed infinite ordinal. A *system of root extensions* is a triple of indexed sets $(\{A_\alpha\}, \{X_\alpha\}, \{\pi_{\alpha,\beta}\})$ ($0 \leq \alpha \leq \beta \leq \tau$) (denoted for brevity by $\{A_\alpha\}_{0 \leq \alpha \leq \tau}$) where each A_α is a uniform algebra, each X_α is a compact space, and each $\pi_{\alpha,\beta}$ is a continuous surjective map $\pi_{\alpha,\beta} : X_\beta \rightarrow X_\alpha$ such that the following conditions hold:

- (i) The equation $\pi_{\alpha,\beta}^*(f) = f \circ \pi_{\alpha,\beta}$ defines a homomorphism of A_α into A_β .
- (ii) For $\alpha \leq \beta \leq \gamma$, $\pi_{\alpha,\beta} \circ \pi_{\beta,\gamma} = \pi_{\alpha,\gamma}$, and $\pi_{\alpha,\alpha}$ is the identity on X_α .
- (iii) For $\alpha < \tau$, there is a subset \mathcal{F}_α of A_α such that $A_{\alpha+1}$ is the \mathcal{F}_α -extension of A_α and $\pi_{\alpha,\alpha+1}$ is the associated surjection.
- (iv) For γ a limit ordinal, X_γ is the inverse limit of the inverse system $\{X_\alpha, \pi_{\alpha,\beta}\}_{\alpha \leq \beta < \gamma}$, the maps $\pi_{\alpha,\gamma} : X_\gamma \rightarrow X_\alpha$ are those associated with the inverse limit, and A_γ is the closure in $C(X_\gamma)$ of $\bigcup_{\alpha < \gamma} \pi_{\alpha,\gamma}^*(A_\alpha)$.

The existence of systems of root extensions is of course proved by transfinite induction. A choice of the subsets \mathcal{F}_α uniquely determines a system of root extensions.

The following is contained in [3, Theorem 2.1]

LEMMA 3.3. *Given a system of root extensions $\{A_\alpha\}_{0 \leq \alpha \leq \tau}$ there is a linear operator $T_\tau : A_\tau \rightarrow A_0$ such that:*

- (i) $\|T_\tau\| = 1$.
- (ii) $T_\tau \circ \pi_{0,\tau}^*$ is the identity.

The following is [5, Corollary 2.9].

LEMMA 3.4. *Given a system of root extensions $\{A_\alpha\}_{0 \leq \alpha \leq \tau}$, if A_0 is normal, then A_α is normal for all α .*

4. Nonzero bounded point derivations in the absence of nontrivial Gleason parts. The following lemma is the key to our construction of a uniform algebra on which there is a nonzero bounded point derivation but which has no nontrivial Gleason parts.

LEMMA 4.1. *Let A be a uniform algebra on a compact space X , and let x be a point of X . Suppose that $d = (d^{(k)})_{k=0}^n$ is a nondegenerate bounded point derivation of order n ($1 \leq n \leq \infty$) at x , and that \mathcal{F} is a subset of $\ker d$. Then there is a nondegenerate bounded point derivation $D = (D^{(k)})_{k=0}^n$ of order n on the \mathcal{F} -extension $A_{\mathcal{F}}$ of A , at the point $y = \pi^{-1}(x)$, satisfying $D^{(k)} \circ \pi^* = d^{(k)}$ and $\|D^{(k)}\| = \|d^{(k)}\|$ for all $k = 0, 1, 2, \dots$.*

Proof. Let $T : A_{\mathcal{F}} \rightarrow A$ be as in Section 3. For each $k = 0, 1, 2, \dots$, define $D^{(k)} : A_{\mathcal{F}} \rightarrow \mathbb{C}$ by

$$D^{(k)} = d^{(k)} \circ T.$$

Clearly $D^{(k)}$ is a bounded linear functional and by Lemma 3.1(ii), $D^{(k)} \circ \pi^* = d^{(k)} \circ T \circ \pi^* = d^{(k)}$. To see that $\|D^{(k)}\| = \|d^{(k)}\|$, note that $\|D^{(k)}\| \leq \|d^{(k)}\| \|T\| = \|d^{(k)}\|$, while also $\|D^{(k)}\| \geq \|d^{(k)}\|$ because for each $f \in A$ we have $D^{(k)}(\pi^*(f)) = d^{(k)}(T(\pi^*(f))) = d^{(k)}f$. In particular, $D^{(1)} \neq 0$, so $D = (D^{(k)})_{k=0}^n$ is nondegenerate. Note also that $D^{(0)}f = f(y)$ for $f \in A_{\mathcal{F}}$.

It remains to show that D satisfies, for each $k = 1, 2, \dots$, the derivation identity

$$(4.1) \quad D^{(k)}(fg) = \sum_{j=0}^k (D^{(j)}f)(D^{(k-j)}g)$$

for all $f, g \in A_{\mathcal{F}}$. It suffices to prove (4.1) for f and g belonging to the dense subalgebra H of $A_{\mathcal{F}}$ that is algebraically generated by $\pi^*(A) \cup \{p_f : f \in \mathcal{F}\}$. Functions f and g in H can be expressed in the form

$$f = \pi^*(f_0) + \sum_{u=1}^s \pi^*(f_u)F_u \quad \text{and} \quad g = \pi^*(g_0) + \sum_{v=1}^t \pi^*(g_v)G_v$$

where $f_0, f_1, \dots, f_s, g_0, g_1, \dots, g_t \in A$ and each F_u and each G_v is a nonempty product of distinct functions of the form p_f for $f \in \mathcal{F}$.

By Lemma 3.1, $Tf = f_0$ and $Tg = g_0$, so for each $r = 0, 1, 2, \dots$,

$$D^{(r)}f = (d^{(r)} \circ T)(f) = d^{(r)}f_0 \quad \text{and} \quad D^{(r)}g = (d^{(r)} \circ T)(g) = d^{(r)}g_0.$$

Since for each $k = 1, 2, \dots$,

$$d^{(k)}(f_0g_0) = \sum_{j=0}^k (d^{(j)}f_0)(d^{(k-j)}g_0),$$

the proof will be complete once we show $D^{(r)}(fg) = d^{(r)}(f_0g_0)$ for each r .

View fg as a sum of four terms:

$$\begin{aligned} fg &= \pi^*(f_0g_0) + \left(\sum_{u=1}^s \pi^*(f_u g_0) F_u \right) + \left(\sum_{v=1}^t \pi^*(f_0 g_v) G_v \right) \\ &\quad + \left(\sum_{u=1}^s \sum_{v=1}^t \pi^*(f_u g_v) F_u G_v \right). \end{aligned}$$

By Lemma 3.1,

$$(4.2) \quad T(\pi^*(f_0 g_0)) = f_0 g_0,$$

$$(4.3) \quad T\left(\sum_{u=1}^s \pi^*(f_u g_0) F_u\right) = 0,$$

$$(4.4) \quad T\left(\sum_{v=1}^t \pi^*(f_0 g_v) G_v\right) = 0.$$

Now for fixed u and v , consider $T(\pi^*(f_u g_v) F_u G_v)$. We have $F_u = p_{f_1} \cdots p_{f_a}$ and $G_v = p_{g_1} \cdots p_{g_b}$ where f_1, \dots, f_a are distinct elements of \mathcal{F} and g_1, \dots, g_b are also distinct elements of \mathcal{F} . Note that each of the sets $\{f_1, \dots, f_a\}$ and $\{g_1, \dots, g_b\}$ is necessarily nonempty. If $\{f_1, \dots, f_a\} = \{g_1, \dots, g_b\}$, then $F_u G_v = p_{f_1}^2 \cdots p_{f_a}^2 = \pi^*(f_1 \cdots f_a)$, and hence

$$(d^{(r)} \circ T)(\pi^*(f_u g_v) F_u G_v) = (d^{(r)} \circ T)(\pi^*(f_u g_v f_1 \cdots f_a)) = d^{(r)}(f_u g_v f_1 \cdots f_a);$$

the last quantity above is zero because f_1, \dots, f_a belong to the ideal $\ker d$. If instead $\{f_1, \dots, f_a\} \neq \{g_1, \dots, g_b\}$, then $F_u G_v$ can be expressed as the product of a possibly empty set of elements of $\pi^*(A)$ and a *nonempty* set of functions p_{h_1}, \dots, p_{h_c} with $h_1, \dots, h_c \in \{f_1, \dots, f_a, g_1, \dots, g_b\}$; consequently, $T(\pi^*(f_u g_v) F_u G_v) = 0$ by Lemma 3.1(iii). We conclude that

$$(4.5) \quad (d^{(r)} \circ T)\left(\sum_{u=1}^s \sum_{v=1}^t \pi^*(f_u g_v) F_u G_v\right) = 0.$$

Collectively, equations (4.2)–(4.5) yield

$$D^{(r)}(fg) = (d^{(r)} \circ T)(fg) = d^{(r)}(f_0 g_0),$$

as desired. ■

THEOREM 4.2. *Let A be a uniform algebra on a compact Hausdorff space Y , and let x_0 be a point of \mathfrak{M}_A . Suppose that there is a nondegenerate bounded point derivation $d = (d^{(k)})_{k=0}^n$ of order n with $1 \leq n \leq \infty$ on A at x_0 . Then there exists a uniform algebra A^D on a compact Hausdorff space Y^D and a continuous surjective map $\pi : \mathfrak{M}_{A^D} \rightarrow \mathfrak{M}_A$ such that:*

- (i) $\pi(Y^D) = Y$.
- (ii) The formula $\pi^*(f) = f \circ \pi$ defines an isometric embedding of A into A^D .
- (iii) $\pi^{-1}(x_0)$ consists of a single point, which we denote by x_ω .
- (iv) There is a nondegenerate bounded point derivation $D = (D^{(k)})_{k=0}^n$ on A^D at x_ω that satisfies the equation $D^{(k)} \circ \pi^* = d^{(k)}$.
- (v) There is a dense subset \mathcal{F} of $\ker D$ such that every member of \mathcal{F} has a square root in \mathcal{F} . If the algebra A is normal, then \mathcal{F} can be chosen so that for every point $y \in Y^D \setminus \{x_\omega\}$ and every compact subset E of $Y^D \setminus \{y\}$, there exists a neighborhood U of y and a function $f \in \mathcal{F}$ such that $f|U = 1$ and $f|E = 0$.

If the maximal ideal space of A is metrizable, then A^D can be chosen so that its maximal ideal space is metrizable as well. If A is normal, then A^D can be chosen so as to be normal as well.

Proof. Let $\Sigma_0 = \mathfrak{M}_A$, and let A_0 denote A regarded as a uniform algebra on Σ_0 . Set $d_0 = d$. Let \mathcal{F}_0 be a dense subset of $\ker d$. If \mathfrak{M}_A is metrizable, choose \mathcal{F}_0 to be countable. (If \mathfrak{M}_A is nonmetrizable, one can take $\mathcal{F}_0 = \ker d$.) If A is normal, then applying Lemma 2.5 shows that we can, and therefore we shall, choose \mathcal{F}_0 such that for every point $y \in \Sigma_0 \setminus \{x_0\}$ and every compact subset E of $\Sigma_0 \setminus \{y\}$ there exists a neighborhood U of y and a function $f \in \mathcal{F}_0$ such that $f|U = 1$ and $f|E = 0$. Now form the \mathcal{F}_0 -extension of A_0 . Denote the resulting uniform algebra by A_1 , the space on which A_1 is defined by Σ_1 , and the associated surjection $\Sigma_1 \rightarrow \Sigma_0$ by π_1 . Recall that then $\pi_1^{-1}(x_0)$ consists of a single point; denote that point by x_1 . If Σ_0 is metrizable, then Σ_1 is metrizable. By Lemma 4.1, there is a nondegenerate bounded point derivation $d_1 = (d_1^{(k)})_{k=0}^n$ of order n on A_1 at x_1 such that $d_1^{(k)} \circ \pi_1^* = d_0^{(k)}$ and $\|d_1^{(k)}\| = \|d_0^{(k)}\|$ for all $k = 0, 1, 2, \dots$. By Lemma 3.2, if A_0 is normal, then so is A_1 .

We then iterate the process of taking root extensions to obtain a sequence $\{(A_m, \Sigma_m, \pi_m, x_m, d_m, \mathcal{F}_m)\}_{m=0}^\infty$ where each A_m is a uniform algebra on Σ_m , if \mathfrak{M}_A is metrizable then so is each Σ_m , each $\pi_m : \Sigma_m \rightarrow \Sigma_{m-1}$ is a surjective continuous map, $x_m = \pi_m^{-1}(x_{m-1})$, $d_m = (d_m^{(k)})_{k=0}^n$ is a nondegenerate bounded point derivation of order n on A_m at x_m such that $d_m^{(k)} \circ \pi_m^* = d_{m-1}^{(k)}$ and $\|d_m^{(k)}\| = \|d_{m-1}^{(k)}\|$ for all $k = 0, 1, 2, \dots$, and each \mathcal{F}_m is a dense subset of $\ker d_m$ such that for every $f \in \mathcal{F}_m$ the function $f \circ \pi_{m+1}$ is the square of a function in \mathcal{F}_{m+1} , and if \mathfrak{M}_A is metrizable, then \mathcal{F}_m is countable; furthermore, if A is normal, then A_m is normal and \mathcal{F}_m is such that for every point $y \in \Sigma_m \setminus \{x_m\}$ and every compact subset E of $\Sigma_m \setminus \{y\}$ there exists a neighborhood U of y and a function $f \in \mathcal{F}_m$ such that $f|U = 1$ and $f|E = 0$. Finally, we take the direct limit of the system of uniform algebras $\{A_m\}$. Explicitly, we set

$$\Sigma_\omega = \left\{ (y_j)_{j=0}^\infty \in \prod_{j=0}^\infty \Sigma_j : \pi_{m+1}(y_{m+1}) = y_m \text{ for all } m = 0, 1, 2, \dots \right\},$$

and letting $q_m : \Sigma_\omega \rightarrow \Sigma_m$ be the restriction of the canonical projection $\prod_{j=0}^\infty \Sigma_j \rightarrow \Sigma_m$, we let A_ω be the closure of $\bigcup_{m=0}^\infty \{h \circ q_m : h \in A_m\}$ in $C(\Sigma_\omega)$. Set $x_\omega = (x_m)_{m=0}^\infty$. Set $\pi = q_0$. Then $\pi^{-1}(x_0) = x_\omega$.

Note that for each $m = 0, 1, 2, \dots$, the formula $q_m^*(f) = f \circ q_m$ defines an isometric embedding of A_m into A_ω , and A_ω is the closure of $\bigcup_{m=0}^\infty q_m^*(A_m)$. Observe that $q_{m+1}^* \circ \pi_{m+1}^* = q_m^*$, and hence $q_m^*(A_m) \subset q_{m+1}^*(A_{m+1})$. Define

$\tilde{d}_m^{(k)}$ ($k = 0, 1, 2, \dots$) on $q_m^*(A_m)$ by

$$\tilde{d}_m^{(k)}(q_m^*(h)) = d_m^{(k)}(h) \quad \text{for all } h \in A_m.$$

One easily checks that $\tilde{d}_{m+1}^{(k)}$ agrees with $\tilde{d}_m^{(k)}$ on $q_m^*(A_m)$ for each m and k . Thus, for each fixed k , the union of the functionals $\tilde{d}_m^{(k)}$, $m = 0, 1, 2, \dots$, yields a well-defined linear functional $\tilde{d}^{(k)}$ on $\bigcup_{m=0}^{\infty} q_m^*(A_m)$. Because the functionals $\tilde{d}_m^{(k)}$, $m = 0, 1, 2, \dots$, all have the same norm $\|\tilde{d}_0^{(k)}\|$, the functional $\tilde{d}^{(k)}$ is bounded, and hence extends to a bounded linear functional $D^{(k)}$ on A_ω . Moreover, $D = (D^{(k)})_{k=0}^n$ is a nondegenerate bounded point derivation of order n on A_ω at x_ω .

By [3, Theorem 2.3], the maximal ideal space of A_ω is Σ_ω , and the inverse image under π of the Shilov boundary for A_0 is the Shilov boundary for A_ω . Consequently, setting $Y^D = \pi^{-1}(Y)$ and A^D equal to the restriction algebra $A_\omega|Y^D$, we find that A^D is a uniform algebra isometrically isomorphic to A_ω . Obviously we can regard the derivation D as a derivation on A^D . Set $\mathcal{F} = \bigcup_{m=0}^{\infty} q_m^*(\mathcal{F}_m)$. As can be verified, conditions (i)–(v) all hold.

Note that if Σ_0 is metrizable, then so is Σ_ω . If A is normal, then so is A^D by Lemma 3.4. ■

LEMMA 4.3. *Let A be a uniform algebra, let J be a primary ideal in A , and let $E = \{f^2 : f \in J\}$. If E is dense in J , then each point of \mathfrak{M}_A is a one-point Gleason part.*

Proof. The proof is similar to that of [3, Lemma 1.1(i)]. Let x be the point of \mathfrak{M}_A such that J is contained in M_x . Let $y \in \mathfrak{M}_A \setminus \{x\}$ be arbitrary, and let z be an arbitrary element of \mathfrak{M}_A distinct from y . By hypothesis there is a function f in J such that $f(y) \neq 0$. By multiplying f by a function in A that vanishes at z but not at y and by rescaling, we may assume in addition that $f(z) = 0$ and $\|f\| < 1$. Since E is dense in J , for each $n \in \mathbb{N}$ and $\varepsilon > 0$, there exist functions f_1, \dots, f_n in J such that $\|f - f_1^2\| < \varepsilon, \dots, \|f_{n-1} - f_n^2\| < \varepsilon$. Choosing $\varepsilon > 0$ small enough, we can make $f_n^{2^n}$ arbitrarily close to f . Consideration of the function $f_n - f_n(z)$ then shows that there is a function g in A such that $g(z) = 0$ and g^{2^n} is arbitrarily close to f . Since $|f(y)|^{2^{-n}} \rightarrow 1$, choosing n large enough can render $|g(y)|$ arbitrarily close to 1. Thus y and z lie in different Gleason parts by Lemma 2.4 ■

Proof of Theorems 1.1 and 1.3. To prove Theorem 1.1 we start with any uniform algebra A that is defined on a compact metrizable space and has a nonzero bounded point derivation of order 1. For instance, take A to be the disc algebra. Then taking B to be the uniform algebra A^D given by Theorem 4.2 yields the result. That B has no nontrivial Gleason parts is a consequence of condition (v) by Lemma 4.3.

To prove the stronger Theorem 1.3 we impose on our starting uniform algebra A the additional requirements that A be normal and that there exist a nondegenerate bounded point derivation of infinite order on A . An example of a uniform algebra satisfying these requirements was given by Anthony O'Farrell [9]. Now take B to be the uniform algebra A^D given by Theorem 4.2 choosing \mathcal{F} as discussed in condition (v). The assertion in Theorem 1.3 about bounded relative units then holds by Lemma 2.2. ■

5. Nontrivial Gleason parts in the absence of nonzero point derivations. In this section we prove Theorems 1.2, 1.4, and 1.5. The uniform algebra we give with the properties in Theorem 1.5 is essentially the uniform algebra constructed by Feinstein in [6]. The uniform algebra constructed in the proof of Theorems 1.2 and 1.4 is a modification of that uniform algebra.

Proof of Theorems 1.2 and 1.4. Start with any normal uniform algebra A that has a Gleason part with at least n points. For instance take A to be the normal uniform algebra constructed by Robert McKissick [8] (which is also presented in [11, Section 27]). Set $(A_0, X_0) = (A, \mathfrak{M}_A)$ and let $x_0^{(1)}, \dots, x_0^{(n)}$ be n distinct points belonging to a common Gleason part for A_0 . Let Ω denote the first uncountable ordinal.

Recall that when forming the \mathcal{F} -extension of a uniform algebra A on a space X , if \mathcal{F} is contained in M_x for a point $x \in X$, then $\pi^{-1}(x)$ consists of a single point. Consequently, one easily sees that there is a system of root extensions $(\{A_\alpha\}, \{X_\alpha\}, \{\pi_{\alpha,\beta}\})$ ($0 \leq \alpha \leq \beta \leq \Omega$) such that:

- (i) for each $0 \leq \gamma \leq \Omega$ there are distinct points $x_\gamma^{(1)}, \dots, x_\gamma^{(n)}$ in X_γ such that $\pi_{\alpha,\beta}^{-1}(x_\alpha^{(j)}) = x_\beta^{(j)}$ for each $1 \leq j \leq n$ and $0 \leq \alpha \leq \beta \leq \Omega$, and
- (ii) for each $0 \leq \alpha < \Omega$, the pair $(A_{\alpha+1}, X_{\alpha+1})$ is the \mathcal{F}_α -extension of (A_α, X_α) with $\mathcal{F}_\alpha = M_{x_\alpha^{(1)}} \cap \dots \cap M_{x_\alpha^{(n)}}$.

Set $\mathcal{F} = M_{x_\Omega^{(1)}} \cap \dots \cap M_{x_\Omega^{(n)}}$, and note that $\mathcal{F} = \bigcup_{0 \leq \alpha < \Omega} \pi_{\alpha,\Omega}^*(\mathcal{F}_\alpha)$. Consequently, every function in \mathcal{F} has a square root in \mathcal{F} . Set $B = A_\Omega$, set $X = X_\Omega$, set $x_j = x_\Omega^{(j)}$ ($j = 1, \dots, n$), and set $P = \{x_1, \dots, x_n\}$.

By Lemma 3.4, B is normal. Applying Lemma 2.2 then implies that B has bounded relative units at every point of $X \setminus P$. Therefore, by Lemma 2.1, every point of $X \setminus P$ is a generalized peak point, and hence is a one-point Gleason part. Consequently, to show that P is a Gleason part, it is enough to show that any two points of P lie in a common Gleason part. For that, note that given $h \in B$ with $\|h\| \leq 1$, the function $T_\Omega h$ is in A_0 with $\|T_\Omega h\| \leq 1$, and so, for $1 \leq j, k \leq n$,

$$|h(x_j) - h(x_k)| = |(T_\Omega h)(x_0^{(j)}) - (T_\Omega h)(x_0^{(k)})| \leq \|x_0^{(j)} - x_0^{(k)}\|;$$

consequently, $\|x_j - x_k\| \leq \|x_0^{(j)} - x_0^{(k)}\|$, and hence x_j and x_k lie in a common Gleason part.

There are no nonzero point derivations on B at points of $X \setminus P$ because each of these points is a generalized peak point. To show that there are no nonzero point derivations on B at points of P , we consider a point $y \in P$ and a function $f \in M_y$ and will show that f is in M_y^2 . There exists $g \in B$ such that $g(x_j)^2 = f(x_j)$ for $j = 1, \dots, n$. Note that g is in M_y . Clearly $f - g^2$ is in \mathcal{F} , so there exists $h \in \mathcal{F}$ such that $f - g^2 = h^2$. Then h is in M_y , and hence so are $g \pm ih$. Since $f = (g + ih)(g - ih)$, we deduce that f is in M_y^2 , as desired. ■

Proof of Theorem 1.5. We first argue essentially as in the proof just given except that instead of using a root system with index set the ordinals less than or equal to Ω , we simply form an infinite sequence of uniform algebras and take a direct limit once (as we did in the proof of Theorem 1.1), and rather than set $\mathcal{F}_\alpha = M_{x_\alpha^{(1)}} \cap \dots \cap M_{x_\alpha^{(n)}}$ we take \mathcal{F}_α to be a *countable dense subset* of $M_{x_\alpha^{(1)}} \cap \dots \cap M_{x_\alpha^{(n)}}$. This yields a uniform algebra \tilde{A} satisfying the properties required of the uniform algebra B with strong regularity replaced by the weaker condition of normality. To obtain a strongly regular uniform algebra, set $B = \tilde{A}_{x_1} \cap \dots \cap \tilde{A}_{x_n}$, where we are using the notation introduced in the paragraph preceding Lemma 2.6. By Corollary 2.9(ii), B has bounded relative units at each point of $X \setminus P$, and hence is strongly regular at each point of $X \setminus P$ by Lemma 2.1. Moreover, by Corollary 2.9(i), B is also strongly regular at each point of P as well. Because B is a subalgebra of \tilde{A} , points in a common Gleason part for \tilde{A} must also lie in a common Gleason part for B . In the present situation, that implies that the Gleason parts for B coincide with the Gleason parts for \tilde{A} . ■

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